A3G560-AP68-23

EC axial fan - HyBlade

sickle-shaped blades (S series)



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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**A3G560-AP68-23**
Motor	**M3G112-EA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1000
Power consumption	W	400
Current draw	A	1.8
Max. back pressure	Pa	100
Max. back pressure	inH2O	0.4
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	41.1	31.2
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		49.9	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.4
09 Air flow q_v	m^3/h	5245
09 Pressure increase p_{fs}	Pa	102
10 Speed (rpm) n	min^{-1}	995
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-118048

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Technical description

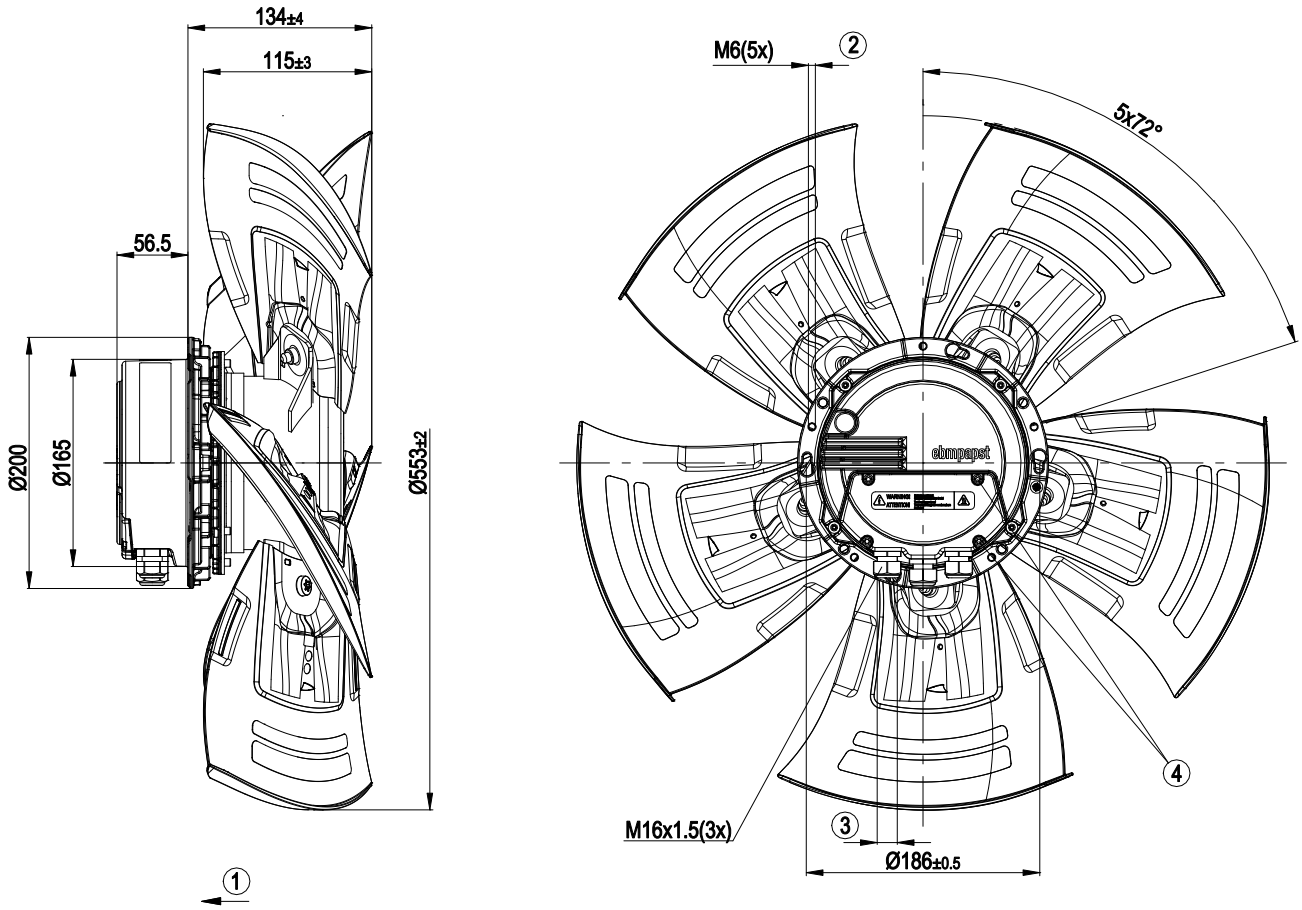
Weight	7.2 kg
Fan size	560 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert, sprayed with PP plastic
Number of blades	5
Blade pitch	-5°
Airflow direction	"V"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Control input 0-10 VDC / PWM - Thermal overload protection for electronics/motor - Alarm relay - PFC, active - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS-485 ebmBUS - Motor current limitation - Soft start - Line undervoltage detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

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Product drawing



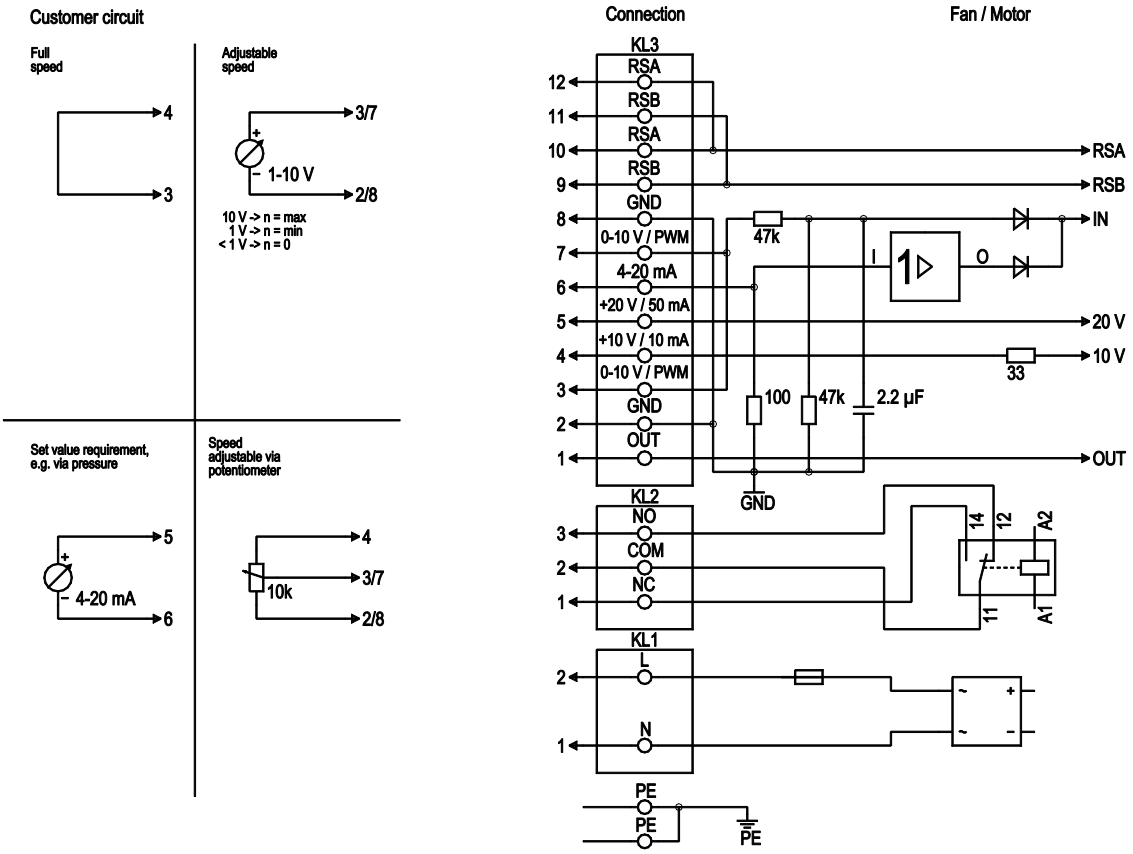
1	Direction of air flow "V"
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection diagram



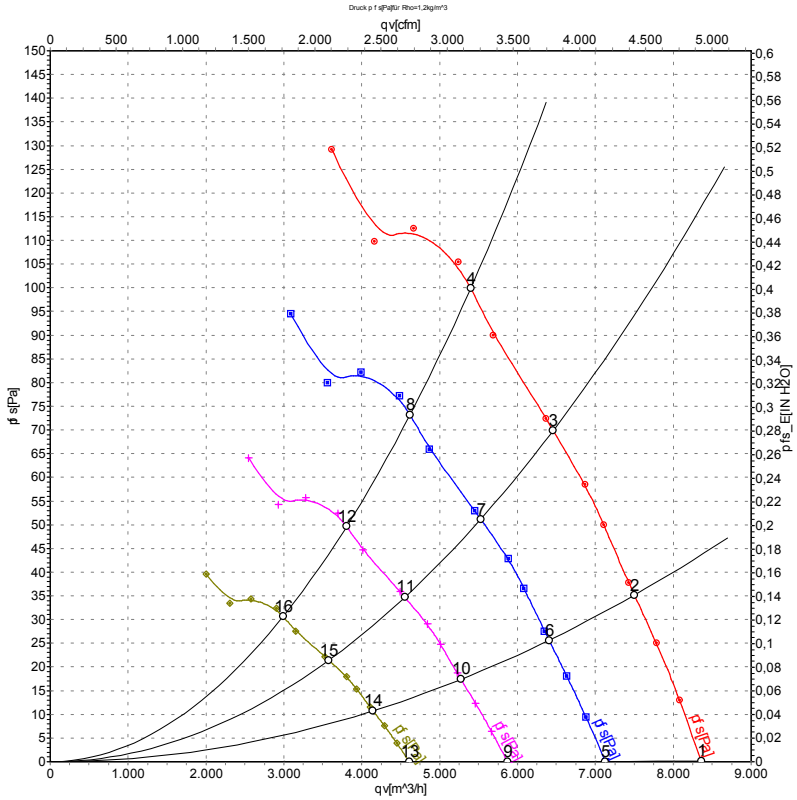
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

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Curves: Air performance 50 Hz



Measurement: LU-118048-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	230	50	1000	293	1.29	60	67	67	8360	0	4920	0.00
2	230	50	1000	336	1.48	59	66	66	7500	35	4415	0.14
3	230	50	1000	369	1.61	60	67	66	6460	70	3800	0.28
4	230	50	1000	400	1.80	62	69	68	5400	100	3175	0.40
5	230	50	850	182	0.80	57	64	64	7130	0	4195	0.00
6	230	50	850	209	0.92	56	63	62	6405	26	3770	0.10
7	230	50	850	231	1.01	57	63	62	5530	51	3255	0.20
8	230	50	850	249	1.09	59	65	65	4620	73	2720	0.29
9	230	50	700	102	0.45	53	59	59	5870	0	3455	0.00
10	230	50	700	117	0.51	52	58	58	5275	17	3105	0.07
11	230	50	700	129	0.57	52	59	58	4550	35	2680	0.14
12	230	50	700	139	0.61	55	61	61	3805	50	2240	0.20
13	230	50	550	49	0.22	47	54	54	4610	0	2715	0.00
14	230	50	550	57	0.25	46	53	53	4145	11	2440	0.04
15	230	50	550	63	0.27	47	54	53	3575	21	2105	0.08
16	230	50	550	68	0.30	49	56	55	2990	31	1760	0.12

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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